

Year 11 Mathematics Higher HT 1

Defin	itions and pro	ocesses			
1.	Magnitude	Size	Denoted using straight lines on either side of the vector $ a $		
2.	Vector	A quantity that has both magnitude and d	lirection	e.g. velocity displacem force	nent
3.	Directed line segment	Can be used to represent a vector		Ľ	В
		Can be written in bold a, with underlining \underline{a} or \overrightarrow{AB}	А	<i>AB</i> or <u>u</u>	
4.	Unit vector	A vector with a magnitude of 1		\mathbf{y}	
		Unit vector in the x direction			$i = \langle 1, 0 \rangle$
		Unit vector in the y direction			1 × x
5.	Column vector	x denotes the horizontal movement	((x)	-←+ ++
		y denotes the vertical movement	(y)	Ļ_
6.	Resultant	The vector sum of two or more vectors			
7.	Displacement	The action of moving something from its place or position			
8.	Scalar	A quantity that has magnitude e.g. speed is the magnitude of the velocity vector			
9.	Colinear	Two vectors that lie on the same line			

10.	Triangle law	$\overrightarrow{OA} + \overrightarrow{AP} = \overrightarrow{OP}$	v P u A
11.	Parallel vectors	Any vector parallel to the vector a may be written as λa , where λ is a non-zero scalar	b If the number is negative (≠ −1) the new vector -2b has a different length and $-\frac{1}{2}b$ the opposite direction.
12.	$\binom{p}{q}$	Can also be written as $p {f i} + q {f j}$	e.g. $5i + 2j = \binom{5}{2}$
13.	Zero vector	$\overrightarrow{OA} + \overrightarrow{AO} = 0$	
14.	Vectors and ratios	If P is A point on AB, dividing AB in the ratio λ : μ	$\overrightarrow{OP} = \overrightarrow{OA} + \frac{\lambda}{\lambda + \mu} \overrightarrow{AB}$



Propo	portion		

1.	Constant of proportionality	Represented by k		
1.		Its value stays the same		
2.	Direct proportion	Two quantities increase at the same rate	e.g. y is directly proportional to x' $y \propto x$ y = kx	
3.	Inverse proportion	One variable increases at a constant rate while the other variable decreases	e.g. 'y is inversely proportional to x' $y \propto \frac{1}{x}$ $y = \frac{k}{x}$	
Graph	n transformat	ions		
4.	y = -f(x)	Reflection in the x axis	y coordinates are multiplied by -1	
5.	y = f(-x)	Reflection in the y axis	x coordinates are divided by -1	
	y = -f(-x)	Reflection in the x axis and then in the y axis	y coordinates are multiplied by -1 AND x	
6.		Equivalent to rotation of 180° about the origin	coordinates are divided by -1	
7.	y = f(x) + a	Franslation by the vector $\begin{pmatrix} 0 \\ a \end{pmatrix}$		
8.	y = f(x + a)	Translation by the vector $\begin{pmatrix} -a \\ 0 \end{pmatrix}$		
9.	y = af(x)	Stretch by scale factor a in the vertical direction, parallel to the y axis	y coordinates are multiplied by a	
10.	y = f(ax)	Stretch by scale factor $\frac{1}{a}$ in the horizontal direction, parallel to the x axis	x coordinates are multied by $\frac{1}{a}$	

Rates of change					
11.	Gradient	The gradient of the tangent to a curve can be used to calcuakte the gradient of a curve at any point	6 5 4 3 2 7 1 1 2 1 1 2 3 -2 -1 0 -1 2 3		
12.	Area under graph	The area under the graph represents the product of the units on the y and x axes	If the graph is a curve then split up into shapes such as trapezia and triangles to find an estimate for the area		
		e.g. for a velocity time graph the area represents the distance travelled	(s/u) poids		